

Knowledge representation languages — a programmer's interface to satisfiability

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McCarthy and Hayes on AI, 1969

- ▶ [...] intelligence has two parts, which we shall call the **epistemological** and the **heuristic**.
The **epistemological** part is the representation of the world in such a form that the solution of problems follows from the facts expressed in the representation.
The **heuristic** part is the mechanism that on the basis of the information solves the problem and decides what to do.
- ▶ Epistemological part → modeling (knowledge representation)
- ▶ Heuristic → search

Declarative programming

- ▶ Problem specification language → modeling
- ▶ Automated reasoning → search (for proofs)

Databases

- ▶ Query specification language → modeling
- ▶ Query execution → search (for records/answers)

Point missed by SAT (in my view)

SAT focused on search

- ▶ Many hard problems reduce to finding models of CNF theories
- ▶ Can be solved by SAT solvers — programs that **search** for models of CNF theories
- ▶ Search for models — the main focus SAT solver developers
- ▶ But how to build reductions? How to generate inputs to SAT solvers?
- ▶ **It is fundamental to provide support for these tasks**
- ▶ **KR can help**

The goal

- ▶ To design and study languages to capture knowledge about environments, their entities and their behaviors

Early proposal (McCarthy)

- ▶ Use classical logic — it is “descriptively universal”
- ▶ Challenges
 - ▶ Qualification problem
 - ▶ Frame problem
 - ▶ Defaults, rules with exceptions, normative statements, conditionals
 - ▶ Definitions and, especially, *inductive* definitions
 - ▶ Negative information

Non-monotonic logics

Proposed in response to challenges of KR

- ▶ Language of logic with non-classical semantics
- ▶ Model preference
 - ▶ **circumscription**
McCarthy 1977
- ▶ Fixpoint conditions defining belief sets
 - ▶ **default logic**
Reiter 1980
 - ▶ **autoepistemic logic**
Moore 1984
 - ▶ **logic programming with stable-model semantics** (more manageable fragment of default logic)
Gelfond-Lifschitz, 1988
 - ▶ **ID-logic**
Denecker 1998, 2000; Denecker-Ternovska 2004

Logic programming with stable-model semantics

Syntax — that of standard logic programming

- ▶ Programs — collections of clauses (in full language of logic)
- ▶ $A \leftarrow B_1, \dots, B_k, \mathbf{not}(C_1), \dots, \mathbf{not}(C_m)$
 - ▶ “if all A_i are computed and none of B_i **can** be computed, then compute A ”

Semantics — stable models

- ▶ Certain Herbrand models of a program P
- ▶ Alternatively — certain models of $ground(P)$
- ▶ A program is viewed as a definition of the collection of its **stable** models
- ▶ departure from traditional logic-programming perspective
- ▶ **Answer-set programming (ASP)**

Graph-coloring example

Description of input: vertices, edges, colors

$vtx(1)$. $vtx(2)$
 $edge(1, 4)$. $edge(3, 2)$
 $color(r)$. $color(g)$. $color(b)$

Problem specification: assignment of colors

$clrd(X, C) \leftarrow vtx(X), color(C), \mathbf{not}(othercolor(X, C))$.
 $othercolor(X, C) \leftarrow clrd(X, D), D \neq C$.

Problem specification: imposing colorability condition

$\leftarrow edge(X, Y), color(C), clrd(X, C), clrd(Y, C)$.

Correctness

- ▶ A set M of ground atoms is a stable model of the 3-coloring program iff
 - ▶ M contains all facts of the program
 - ▶ for every vertex v , there is exactly one color c such that $clrd(v, c)$ is in M , and for every $d \neq c$, $othercolor(v, c) \in M$
 - ▶ for every edge (u, v) , if $clrd(u, c) \in M$, then $clrd(v, c) \notin M$
- ▶ 1-to-1 correspondence with proper 3-colorings of G
- ▶ Given a stable model, the corresponding coloring can be reconstructed easily and quickly

Answer-Set Programming (ASP)

- ▶ **Code** computational problems as logic programs so that stable models correspond to solutions
 - ▶ disallowing function symbols in the language guarantees finiteness of ground programs and their stable models
- ▶ **Ground** the program — **bridge from modeling to search**
- ▶ **Search** — find stable models of the ground program
 - ▶ search problem similar to SAT and with the same complexity
 - ▶ place for SAT solvers and SAT techniques
- ▶ **Output** — recover solutions from stable models

Expressive power of ASP

Uniform encoding of a search problem Π

- ▶ Problem specification

$clrd(X, C) \leftarrow vtx(X), color(C), \mathbf{not}(othercolor(X, C)).$
 $othercolor(X, C) \leftarrow clrd(X, D), D \neq C.$
 $\leftarrow edge(X, Y), color(C), clrd(X, C), clrd(Y, C).$

- ▶ Description of input

$vtx(1). vtx(2). \dots$
 $edge(1,4). edge(3,2). \dots$
 $color(r). color(g). color(b). \dots$

Expressive power

- ▶ the class of problems that can be represented in this way by finite programs

Finite programs w/out function symbols capture precisely the class NPMV

- ▶ NPMV — the class of all search problems computed by polynomial-time non-deterministic **transducers**

*transducers: non-deterministic Turing Machine-like devices that compute partial multivalued functions from strings to strings, that is, **search problems***

Advantages

- ▶ Stable-model semantics addresses several of KR challenges
- ▶ Gives rise to an effective KR system
reasoning about action, planning, ... ; Gelfond-Leone 2001, Baral 2002
- ▶ Comes with modeling language
- ▶ Comes with computational support
lparses/models; Niemelä-Simons-Syrjänen
dlv; Leone-Eiter-Faber-Pfeifer, ...
- ▶ Can it be used as an interface to SAT solvers?
not directly but essentially yes; more on this later ...

Stable-model semantics also a problem

- ▶ Coding — stable models not a household name
- ▶ Computing — methods to compute stable models recieved relatively little attention

Alternatives?

- ▶ Stay closer to classical logic

Language of predicate logic, essentially

- ▶ Sets of constant, variable and predicate symbols (no function symbols)
- ▶ Equality symbol “=”
- ▶ Boolean connectives:
 - ▶ \wedge we will write: $\&$
 - ▶ \vee we will write: $|$
 - ▶ \rightarrow
- ▶ square brackets “[” and “]” for existential quantification
- ▶ Terms: constant and variable symbols
- ▶ Atoms and ground atoms
- ▶ **Eq-atom**: $p(t)[X, Y, \dots]$ (stands for: $\exists X \exists Y \dots p(t)$)

Formulas and theories

▶ PS-clauses

- ▶ $A_1, \dots, A_m \rightarrow B_1 \mid \dots \mid B_n.$
- ▶ A_i — atoms
- ▶ B_i — atoms or eq-atoms
- ▶ implicitly universally quantified
- ▶ implication notation better aligned with typical natural language specs of constraints

▶ PS-theories

- ▶ **finite** sets of PS-clauses with at least **one** constant

Example — graph-coloring problem

Every vertex gets at least one color

- ▶ $vtx(X) \rightarrow clrd(X, C)[C]$.

For every edge, its vertices are colored differently

- ▶ $edge(X, Y), clrd(X, C), clrd(Y, C) \rightarrow .$

Models of a PS-theory T

- ▶ Herbrand models with $HU(T)$ as the domain
- ▶ Equivalently, subsets of $HB(T)$
- ▶ Or, truth assignments to atoms from $HB(T)$

ground(T)

- ▶ a, b, \dots — all constants in a PS-theory T
- ▶ R — a PS-clause in T
- ▶ $\mathit{ground}(R)$ — set of propositional clauses obtained by:
 - ▶ replacing R by all its ground instances (substitute free variables with constants)
 - ▶ eliminating existential quantification — replacing eq-atoms with disjunctions

$$p(t)[X] \longrightarrow p(t_{X/a}) \mid p(t_{X/b}) \mid \dots$$

- ▶ $\mathit{ground}(T) = \{\mathit{ground}(R) : R \in T\}$

Example

$vtx(X) \rightarrow clrd(X, C)[C]$.

- ▶ Assume: vertices 1, 2, 3; colors a, b
- ▶ Step 1:
 $vtx(2) \rightarrow clrd(2, C)[C]$ (one of the instantiations)
- ▶ Step 2:
 $vtx(2) \rightarrow clrd(2, a) \mid clrd(2, b) \mid clrd(2, 1) \mid clrd(2, 2) \mid clrd(2, 3)$

Propositional characterization of models of PS-theories

- ▶ Models of $ground(T)$ = models of T

Program-data pairs

- ▶ Problem specifications should be independent of instances
- ▶ Program-data pair: (P, D)
 - ▶ P — **program**: PS-theory to specify a problem
 - ▶ D — **data**: set of ground atoms to describe a problem instance
- ▶ **Data predicates** — those that appear in D
- ▶ **Program predicates** — all other predicates in P

Graph-coloring problem

Program P

- ▶ $vtx(X) \rightarrow clrd(X, C)[C]$.
- ▶ $clrd(X, C), clrd(X, D) \rightarrow C = D$.
- ▶ $edge(X, Y), clrd(X, C), clrd(Y, C) \rightarrow .$
- ▶ $clrd(X, C) \rightarrow vtx(X)$. (typing)
- ▶ $clrd(X, C) \rightarrow color(C)$. (typing)

Data (instance) D

- ▶ $vtx(1), vtx(2), vtx(3), vtx(4)$.
- ▶ $edge(1, 2), edge(1, 3), edge(2, 4), edge(4, 3)$.
- ▶ $color(r), color(b), color(g)$

$CWA(D)$

- ▶ Intended meaning of D — a **complete** specification of a data instance
- ▶ For every data-predicate ground atom not listed explicitly in D , **assume its negation**
 - ▶ no $vtx(b)$ in D
 - ▶ b is not a vertex
 - ▶ $\neg vtx(b)$ holds
- ▶ $CWA(D) = D \cup \{\neg p(t) : p - \text{data predicate, } t - \text{ground, } p(t) \notin D\}$

Models of (P, D)

- ▶ Meaning of a program-data pair (P, D) — PS-theory $P \cup CWA(D)$
- ▶ Models of a program-data pair (P, D) — models of $P \cup CWA(D)$

Graph-coloring example

Correctness of the encoding

- ▶ G — a graph
- ▶ P — coloring program as described above (with typing)
- ▶ D — a set of ground atoms specifying G and the colors
- ▶ Colorings of G are in one-to-one correspondence to models of (P, D)

Uniform encodings

- ▶ Program-data pairs — separation of problem specification from instance description
- ▶ Problem specification — a finite PS program
- ▶ Expressive power — the class of problems that can be represented by finite PS programs
- ▶ **Finite PS programs capture precisely the class NPMV**

Coding a search problem

- ▶ Select the language:
 - ▶ a schema to represent problem instances
 - ▶ appropriate program predicates
- ▶ Specify the problem as a PS-theory (program) P

Solving for an instance D

- ▶ Compute models of (P, D) , that is, models of $CWA(D) \cup P$
- ▶ Ground $CWA(D) \cup P$
- ▶ Simplify: use $CWA(D)$ and typing
- ▶ Search for a model
- ▶ **Can use SAT solvers directly!**

Tools

- ▶ Grounder *psgrnd* — outputs CNF theories (DIMACS)
- ▶ Your favorite SAT solver — computes solutions

Model-extension problem

- ▶ Given a FO formula φ and a finite structure A_I for vocabulary $\sigma \subseteq \text{vocab}(\varphi)$
- ▶ Is there a structure A — an extension of A_I to $\text{vocab}(\varphi)$ — such that $A \models \varphi$?
- ▶ NEXPTIME-complete

Model-extension problem *parametrized*

- ▶ Fix φ and σ
- ▶ Input: finite structure A_I for the vocabulary σ
- ▶ More general version of logic PS (no restriction to conjunctions of clauses)
- ▶ Captures class NPMV

What's missing from logic PS?

Inductive definitions

- ▶ Expressing some concepts neither straightforward nor concise
- ▶ Case in point: **inductive definitions (IDs)** for instance, transitive closure of a graph
- ▶ ID-logic addresses the problem!

Integrates inductive definitions with FOL

- ▶ Inductive definitions
 - ▶ logic programs with the well-founded semantics
- ▶ Intuitive semantics
- ▶ Semantics grounded in algebra of operators on lattices and their fixpoints
- ▶ Directly extends logic PS
- ▶ Simple and concise encoding of logic programs with stable model semantics
- ▶ Addresses major KR problems
 - Denecker-Ternovska on ID-logic and situation calculus, 2004*
- ▶ Computational support — in progress

A common pattern

- ▶ Coding (modeling) — place for KR
- ▶ Grounding — bridge
- ▶ Search (model finding) — place for SAT
- ▶ Output (recovering solutions from models)

Languages

- ▶ Logic programming with stable model semantics (roots in KR)
- ▶ Logic PS (close to classical logic)
- ▶ ID-logic (a common extension)
work on specific modeling syntax in progress

Support for “high-level” constraints

- ▶ Substantial theoretical work — emerging consensus on the semantics

Denecker-Bruynooghe-Pelov 2005; Pontelli-Son 2003-05; Faber-Leone-Pfeifer 2004; Marek-Niemelä-MT 2004; Liu-MT 2005

- ▶ Currently mostly pseudo-boolean (weight) constraints

For every vertex y the sum of weights of vertices in U reachable from y is at least k

$k\{\text{selected_to_}U(X) = w(X)[X] : \text{edge}(Y, X)\}$

$L\{p(t) = w(t)[X] : \text{cond}(s)\}U$

- ▶ Need for standardized high-level syntax

Modeling methodology

- ▶ KR focused on representing knowledge needed to create intelligent reasoning agents
Modeling search problems poses different challenges
- ▶ When to use LP, PS or ID logic?
Does it make a difference as they have the same expressive power (assuming no function symbols)?

Program optimization

- ▶ Program equivalence
- ▶ Optimization by replacing parts of programs with other equivalent ones

Much theoretical work: Lifschitz-Pearce-Valverde 2001; Turner 2003; Lin 2002; Eiter-Fink-Woltran 2003-05; MT 2006

Debugging support

- ▶ Detecting syntactic errors easy — still needs to be done
- ▶ Support for verifying semantic correctness — a major problem mostly untouched

A bridge to search

- ▶ Logic programming (with extensions): [lparse](#), [dlv](#)
- ▶ Logic PS with pseudo-boolean atoms and monotone IDs: [psgrnd](#)
- ▶ Logic ID — grounders under development
- ▶ For many problems grounding is a bottleneck
 - ▶ astronomical sizes of ground theories
 - ▶ time needed to produce them

Interleave grounding and search — tighter integration

- ▶ Non-ground program (theory) as data structure for the ground counterpart
- ▶ Search w/out grounding
proposed by Ginsberg and Parkes, 2002
- ▶ Search with partial grounding only

Search (model finding) — a place for SAT

Native solvers

- ▶ **smodels** and **dlv** for logic programming
- ▶ **aspps** and **wsat(plpb)** for logic PS (with extensions)
- ▶ SAT and PB(SAT) can provide ideas and techniques
 - ▶ clause learning, restarts, data structures
- ▶ Not much of it incorporated so far

Direct use of SAT and PB(SAT)

- ▶ Translations of grounder output to DIMACS and OPT
- ▶ Straightforward for logic PS (and implemented)
- ▶ Less straightforward for logic programming and ID-logic

*program completion and loop formulas; Lin-Zhao 2002,
Giunchiglia-Lierler-Maratea 2004
Denecker; Mitchell-Ternovska in progress*

Main points

- ▶ Knowledge representation languages (LP with stable-model semantics, logic PS, logic ID) offer an interface to satisfiability
- ▶ KR and SAT together open a way to general-purpose, flexible and fast programming environments for solving search problems
- ▶ However, major research challenges still unresolved and must be tackled for this method of solving search problems to gain broader acceptance

Links and References

Links to software

- ▶ *psgrnd/aspps* — www.cs.uky.edu/ai/
- ▶ *lparse/smodels* — www.tcs.hut.fi/Software/smodels/
- ▶ *dlv* — www.tuwien.ac.at/proj/dlv/

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